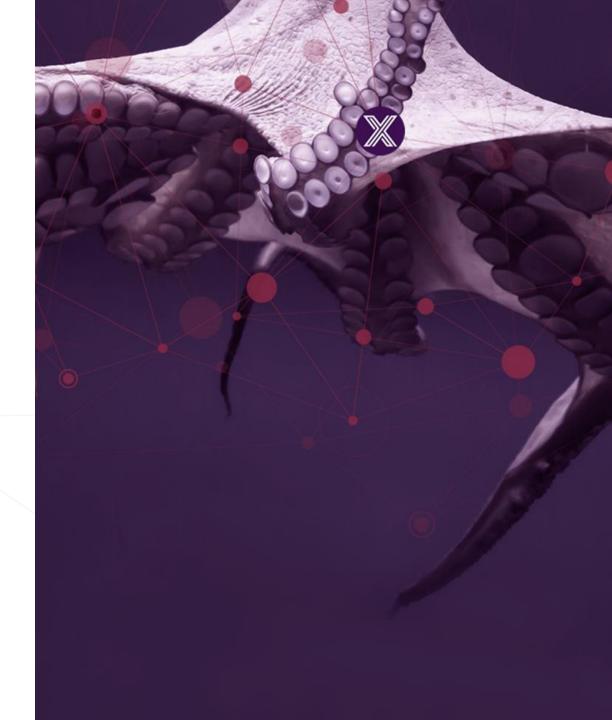
EDGE X FOUNDRY

EdgeX DevKits

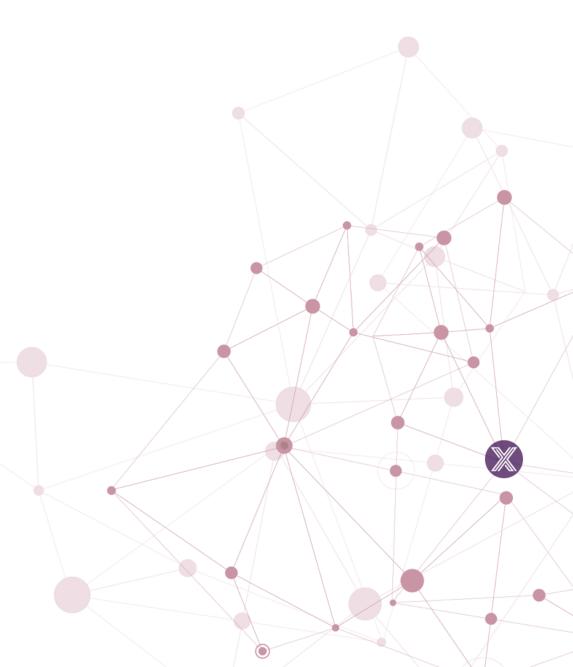
Tech Talks – Session 12





Today's Agenda

- What are EdgeX DevKits?
- EdgeX reminder/overview
- The first EdgeX Community DevKit
 - Raspberry Pi and Grove Sensors
 - Grove Device Service
 - How to use it
 - Example scenario
- Demo
- Q & A

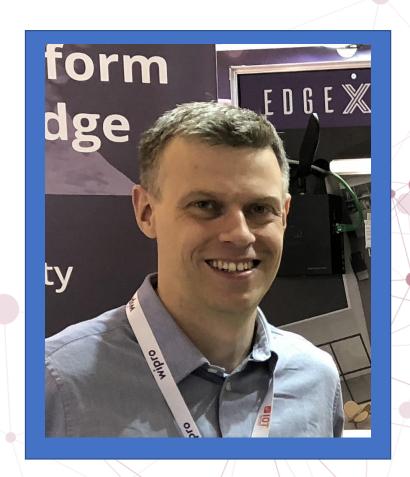




James Butcher

- Senior Solutions Architect at IOTech
- 15 years working in middleware and IoT
- Focused on usability, adoption and roll-out of the technology
- Email james@iotechsys.com







What are EdgeX DevKits?

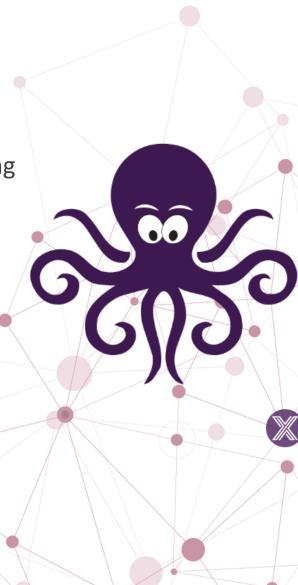
- Aimed at helping users get started quickly with EdgeX
- Pre-configured software to work against specific hardware and sensor combinations
- Good for learning EdgeX get real sensor data flowing quickly
- Can easily sketch out and prototype Edge IoT Proof of Concepts
- Verify real use cases with the sensors and then transition to real/industrial devices
- Both Community and Commercial DevKit options available





Introducing EdgeX Foundry

- An open source, vendor neutral project (and ecosystem)
- A micro service, loosely coupled software framework for IoT edge computing
- Hardware and OS agnostic, optional use of containers
- Linux Foundation, Apache 2 project
- Goal: enable and encourage growth in IoT solutions
 - The community builds and maintains common building blocks and APIs
 - Plenty of room for adding value and getting a return on investment
 - Collaborative approach, allowing best-of-breed solutions



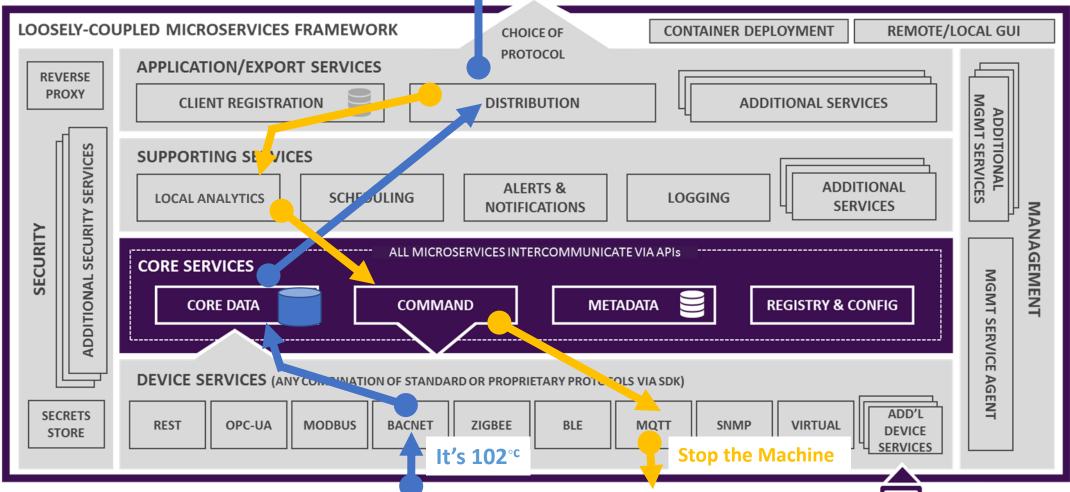
Platform Architecture

Cloud, Enterprise,
On-Prem...

REQUIRED INTEROPERABILITY FOUNDATION

REPLACEABLE REFERENCE SERVICES

"NORTHBOUND" TRASTRUCTURE AND APPLICATIONS

























EdgeX Micro Service Layers

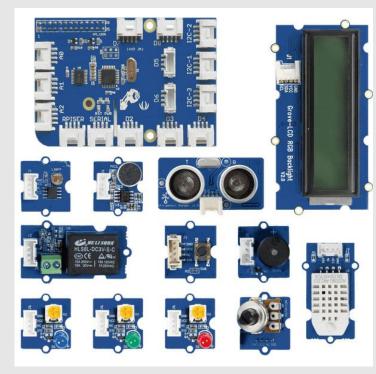
- Contextually, EdgeX micro services are divided into 4 layers
- Crudely speaking, the layers of EdgeX provide a dual transformation engine
 - 1x Translating information coming from sensors and devices via hundreds of protocols and thousands of formats into EdgeX
 - 2x Delivering data to applications, enterprises and cloud systems over TCP/IP based protocols in formats and structures of customer choice
- The DevKits are going to use and demonstrate all of the layers!





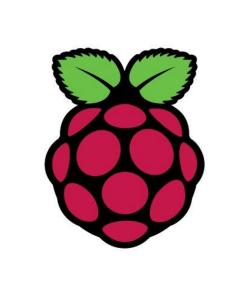
What are Grove Sensors?

- Seeed Studios Grove Kit consist of the base shield and numerous available sensors
- Supported on Raspberry Pi and other dev boards
- Communicates via I2C interface
- Sensors use GPIO/AIO pins
- Light, Sound, Rotary Angle, Relay, LEDs, LCD, Buzzer, etc
- Easy to use, low cost and widely available







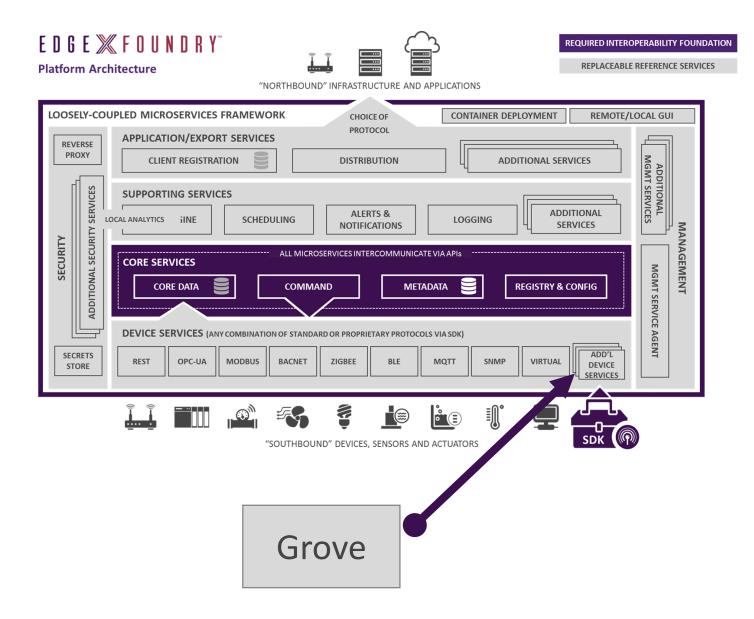




An EdgeX Grove Device Service

EDGE X FOUNDRY

- Needed to write a southbound Device Service that can interface with the **Grove Devices**
- Implemented with C Device Service SDK
- Based on open source libmraa https://github.com/intel-iotdevkit/mraa/
- Requires Device Profile (see next page)
- Typically ran as Docker container with default port 49992



Grove Device Profile

- Maps each sensor's input/output to EdgeX variables within an EdgeX Device (see table)
- Initially supports sensors from GrovePi+ starter kit
- Two options:
 - Single Grove Device which lists Resources & Commands all of the sensors
 - 2. Multiple Grove Devices with Resources & Commands for each sensor
- Default profile automatically creates a single device named "GroveDevice" – i.e. option 1
- /res/configuration.toml and /res/Grove_Device.yaml
- Individual devices modelled as yaml files under /profiles



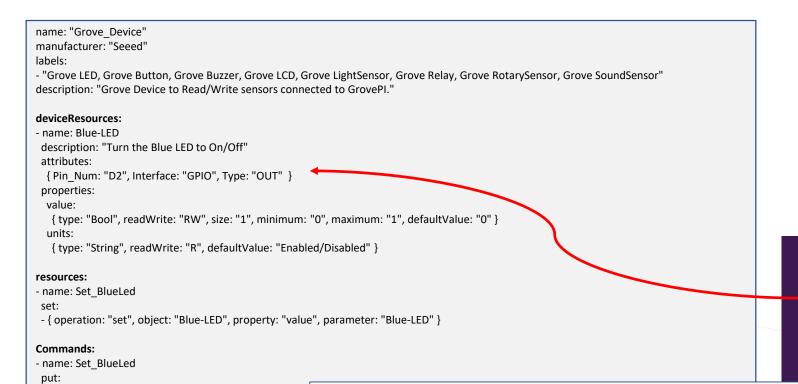


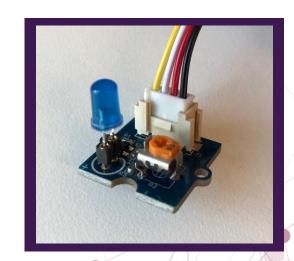
Port	Interface	Grove Sensor
D2	GPIO	Blue LED
D3	GPIO	Green LED
D4	GPIO	Button
D6	GPIO	Red LED
D7	GPIO	Relay
D8	GPIO	Buzzer
Α0	AIO	Light Sensor
A1	AIO	Sound Sensor
A2	AIO	Rotary Angle Sensor
I2C-2	I2C	RGB Backlit LCD



Grove Device Profile – Blue LED example







Port	Interface	Grove Sensor
D2	GPIO	Blue LED
D3	GPIO	Green LED
D4	GPIO	Button

GPIO

GPIO

AIO

AIO

To turn LED on:

path: "/api/v1/device/{deviceId}/Set BlueLed"

parameterNames: ["Blue-LED"]

description: "valid and accepted"

description: "service unavailable"

responses:

- code: "204"

- code: "503"

expectedValues: [] - code: "400"

expectedValues: []

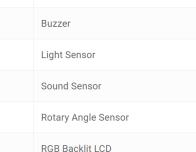
description: "bad request" expectedValues: []

curl '{" BlueLED": "true"}' http://localhost:49992/api/v1/device/all/Set BlueLed

To turn LED off:

curl '{"BlueLED": "false"}' http://localhost:49992/api/v1/device/all/Set BlueLed

12C-2 I2C



Red LED

Relay



EDGE X FOUNDRY

Where to get an EdgeX DevKit?

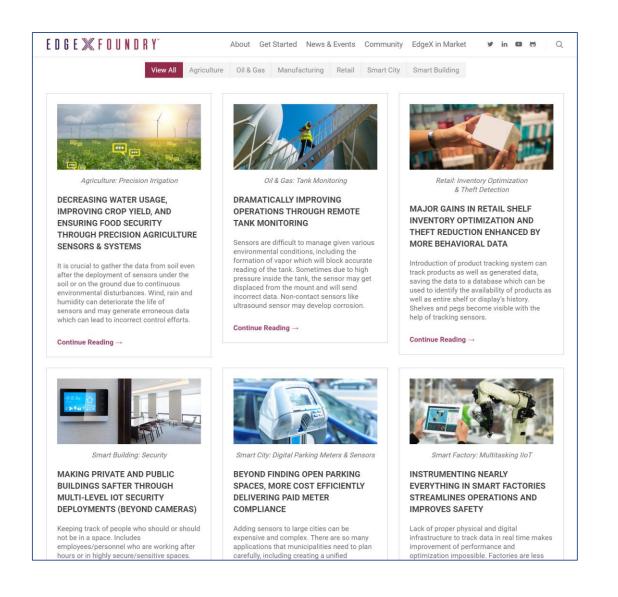
- Community and Commercial DevKit options referenced from EdgeX website
- First EdgeX Community version just released:
 - Raspberry Pi 3 64 bit with GrovePi+ Sensors
 - See https://www.edgexfoundry.org/devkits/
 - Links to buy a Pi and GrovePi+ Sensor Kit
 - Instructions to install custom 64 bit Ubuntu OS image
 - Instructions to download and run the EdgeX software



Aim to Validate Real Use Cases



- Simulate real world scenarios with easy to use sensors
- Can span multiple industries and use cases
- Collect, visualize and make decisions with real data at the edge
- Prove there is value in the project
- Verify that EdgeX technology helps with this
- Evolve to use more industrial devices





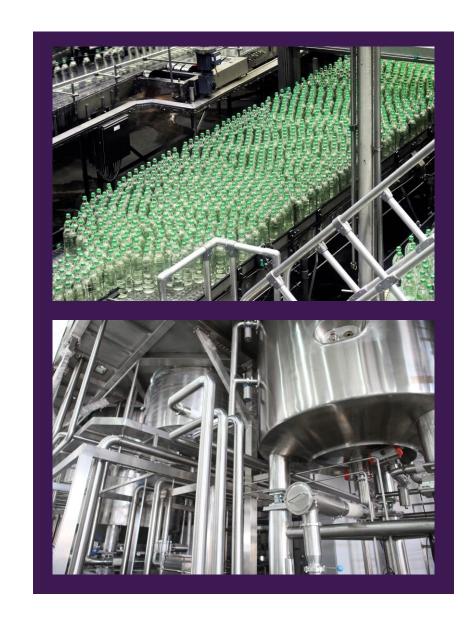
Today's DevKit Demo – Smart Factory

Production / Output Quality Monitoring

- Validate that the factory output meets required QA levels
- e.g. bottles, cartons, packages, etc
- Monitor and analyze size and weight of each item
- Actuate control devices

Production Line / Machine Monitoring

- Validate machinery is operating correctly
- Safety of human operators
- Spot performance degradation ahead of breakage
- Perform timely maintenance routines
- Visualize on dashboards
- Send to Cloud for storage and analysis





Today's DevKit Demo – Smart Factory

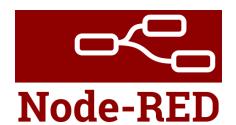
What does the demo do?

- Collect sensor data from some of the Grove Sensors with Grove Device Service
- Ingest into EdgeX through Core Services
- Translate data to northbound side, e.g. to MQTT
- Display data and make decisions at the Edge, e.g. with Node-RED:
 - Easy dashboarding
 - Flow programming capability
 - MQTT subscriptions to get data
 - REST calls to actuate



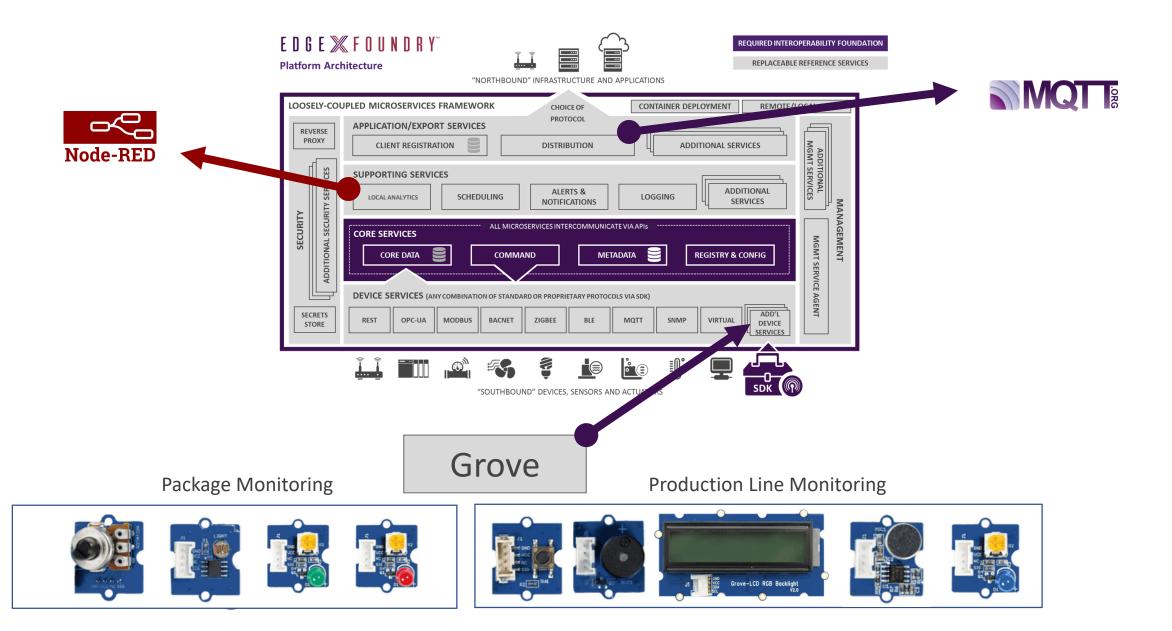
For convenience, Mosquito broker and Node-RED both come pre-installed on supplied Ubuntu Image





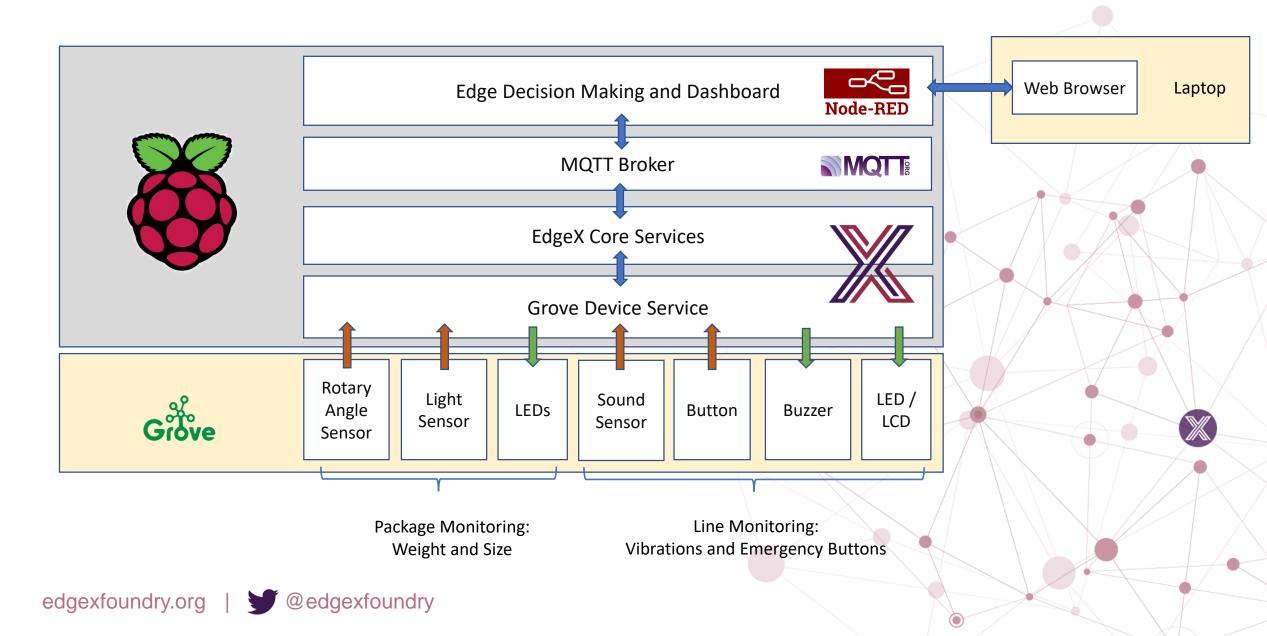
Today's DevKit Demo – EdgeX Architecture





Today's DevKit Demo - Physical Architecture



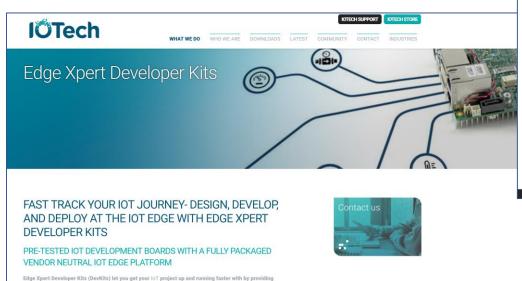


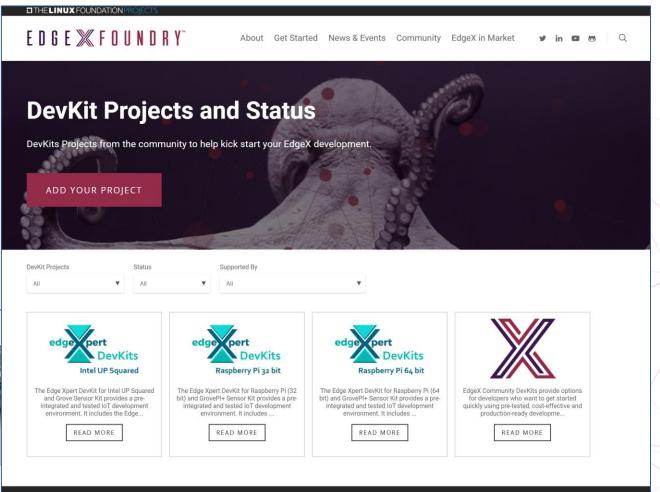


Following On

EDGE X FOUNDRY

- More DevKits different environments and sensors
- Sample use cases for different industries
- Blogs/Videos/Tutorials





Key Project Links



Access the code:

https://github.com/edgexfoundry

Access the technical documentation:

https://docs.edgexfoundry.org/

Access technical video tutorials:

https://wiki.edgexfoundry.org/display/FA/EdgeX +Tech+Talks

EdgeX Blog:

https://www.edgexfoundry.org/news/blog/

Join an email distribution:

https://lists.edgexfoundry.org/mailman/listinfo

Join the Slack Channels:

https://edgexfoundry.slack.com

Become a project member:

https://www.edgexfoundry.org/about/members/join/

LinkedIn:

https://www.linkedin.com/company/edgexfoundry/

Twitter:

https://twitter.com/EdgeXFoundry

Youtube:

https://www.youtube.com/edgexfoundry

EdgeX DevKits:

https://www.edgexfoundry.org/devkits/communitydevkit/

Question and Answer Time





Email: james@iotechsys.com